

Druid: Open Source Real-time Analytics at Scale

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ABSTRACT

Druid is an open source¹ data store built for exploratory analytics on large data sets. Druid supports fast data aggregation, low latency data ingestion, and arbitrary data exploration. The system combines a column-oriented storage layout, a distributed, shared-nothing architecture, and an advanced indexing structure to return queries on billions of rows in milliseconds. Druid is petabyte scale and is deployed in production at several technology companies.

1. INTRODUCTION

The recent proliferation of internet technology has created a surge in machine-generated events. Individually, these events contain minimal useful information and are of low value. Given the time and resources required to extract meaning from large collections of events, many companies were willing to discard this data instead.

A few years ago, Google introduced MapReduce as their mechanism of leveraging commodity hardware to index the internet and analyze logs. The Hadoop project soon followed and was largely patterned after the insights that came out of the original MapReduce paper. Hadoop has contributed much to helping companies convert their low-value event streams into high-value aggregates for a variety of applications such as business intelligence and A-B testing.

As with a lot of great systems, Hadoop has opened our eyes to a new space of problems. Specifically, Hadoop excels at storing and providing access to large amounts of data, however, it does not make any performance guarantees around how quickly that data can be accessed. Furthermore, although Hadoop is a highly available system, performance degrades under heavy concurrent load. Lastly, while Hadoop works well for storing data, it is not optimized for ingesting data and making that data immediately readable.

¹<https://github.com/metamx/druid>

1.1 The Need for Druid

Druid was originally designed to solve problems around ingesting and exploring large quantities of transactional events (log data). This form of timeseries data (OLAP data) is commonly found in the business intelligence space and the nature of the data tends to be very append heavy. Events typically have three distinct components: a timestamp column indicating when the event occurred, a set of dimension columns indicating various attributes about the event, and a set of metric columns containing values (usually numeric) that can be aggregated. Queries are typically issued for the sum of some set of metrics, filtered by some set of dimensions, over some span of time.

The Druid project first began out of necessity at Metamarkets to power a business intelligence dashboard that allowed users to arbitrarily explore and visualize event streams. Existing open source Relational Database Management Systems, cluster computing frameworks, and NoSQL key/value stores were unable to provide a low latency data ingestion and query platform for an interactive dashboard. Queries needed to return fast enough to allow the data visualizations in the dashboard to update interactively.

In addition to the query latency needs, the system had to be multi-tenant and highly available, as the dashboard is used in a highly concurrent environment. Downtime is costly and many businesses cannot afford to wait if a system is unavailable in the face of software upgrades or network failure. Finally, Metamarkets also wanted to allow users and alerting systems to be able to make business decisions in “real-time”. The time from when an event is created to when that event is queryable determines how fast users and systems are able to react to potentially catastrophic occurrences in their systems.

The problems of data exploration, ingestion, and availability span multiple industries. Since Druid was open sourced in October 2012, it has been deployed as a video, network monitoring, operations monitoring, and online advertising analytics platform at multiple companies².

2. ARCHITECTURE

A Druid cluster consists of different types of nodes and each node type is designed to perform a specific set of things. We believe this design separates concerns and simplifies the

²<http://druid.io/druid.html>

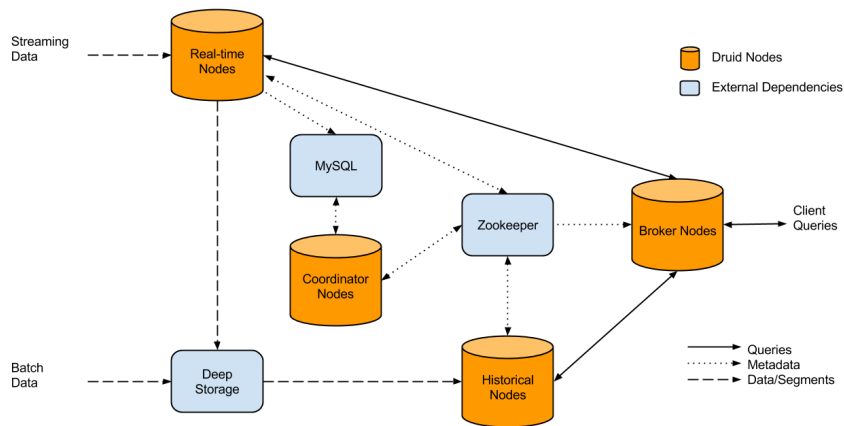


Figure 1: An overview of a Druid cluster and the flow of data through the cluster.

complexity of the system. The different node types operate fairly independently of each other and there is minimal interaction among them. Hence, intra-cluster communication failures have minimal impact on data availability. To solve complex data analysis problems, the different node types come together to form a fully working system. The composition of and flow of data in a Druid cluster are shown in Figure 1. All Druid nodes announce their availability and the data they are serving over Zookeeper[3].

2.1 Real-time Nodes

Real-time nodes encapsulate the functionality to ingest and query event streams. Events indexed via these nodes are immediately available for querying. These nodes are only concerned with events for some small time range. They periodically hand off batches of immutable events to other nodes in the Druid cluster that are specialized in dealing with batches of immutable events.

Real-time nodes maintain an in-memory index buffer for all incoming events. These indexes are incrementally populated as new events are ingested and the indexes are also directly queryable. To avoid heap overflow problems, real-time nodes persist their in-memory indexes to disk either periodically or after some maximum row limit is reached. This persist process converts data stored in the in-memory buffer to a column oriented storage format. Each persisted index is immutable and real-time nodes load persisted indexes into off-heap memory such that they can still be queried. On a periodic basis, each real-time node will schedule a background task that searches for all locally persisted indexes. The task merges these indexes together and builds an immutable block of data that contains all the events that have ingested by a real-time node for some span of time. We refer to this block of data as a “segment”. During the hand-off stage, a real-time node uploads this segment to permanent backup storage, typically a distributed file system that Druid calls “deep storage”.

2.2 Historical Nodes

Historical nodes encapsulate the functionality to load and serve the immutable blocks of data (segments) created by real-time nodes. In many real-world workflows, most of the data loaded in a Druid cluster is immutable and hence historical nodes are typically the main workers of a Druid cluster.

Historical nodes follow a shared-nothing architecture and there is no single point of contention among the nodes. The nodes have no knowledge of one another and are operationally simple; they only know how to load, drop, and serve immutable segments.

2.3 Broker Nodes

Broker nodes act as query routers to historical and real-time nodes. Broker nodes understand what segments are queryable and where those segments are located. Broker nodes route incoming queries such that the queries hit the right historical or real-time nodes. Broker nodes also merge partial results from historical and real-time nodes before returning a final consolidated result to the caller.

2.4 Coordinator Nodes

Druid coordinator nodes are primarily in charge of data management and distribution on historical nodes. The coordinator nodes tell historical nodes to load new data, drop outdated data, replicate data, and move data to load balance. Coordinator nodes undergo a leader-election process that determines a single node that runs the coordinator functionality. The remaining coordinator nodes act as redundant backups.

A coordinator node runs periodically to determine the current state of the cluster. It makes decisions by comparing the expected state of the cluster with the actual state of the cluster at the time of the run. Coordinator nodes also maintain a connection to a MySQL database that contains additional operational parameters and configurations. One of the key pieces of information located in the MySQL database is a table that contains a list of all segments that should be served by historical nodes. This table can be updated by any service that creates segments, such as real-time nodes.

2.5 Query Processing

Data tables in Druid (called *data sources*) are collections of timestamped events partitioned into a set of segments, where each segment is typically 5–10 million rows. Formally, we define a segment as a collection of rows of data that span some period in time. Segments represent the fundamental storage unit in Druid and replication and distribution are done at a segment level.

Timestamp	City	Revenue
2014-01-01T01:00:00Z	San Francisco	25
2014-01-01T01:00:00Z	San Francisco	42
2014-01-01T02:00:00Z	New York	17
2014-01-01T02:00:00Z	New York	170

Table 1: Sample sales data set.

Druid segments are stored in a column orientation. Given that Druid is best used for aggregating event streams (all data going into Druid must have a timestamp), the advantages storing aggregate information as columns rather than rows are well documented [1]. Column storage allows for more efficient CPU usage as only what is needed is actually loaded and scanned.

Druid has multiple column types to represent various data formats. Depending on the column type, different compression methods are used to reduce the cost of storing a column in memory and on disk. For example, if an entire column only contains string values, storing the raw strings is unnecessarily costly. String columns can be dictionary encoded instead. Dictionary encoding is a common method to compress data in column stores.

In many real world OLAP workflows, queries are issued for the aggregated results of some set of metrics where some set of dimension specifications are met. Consider Table 1. An example query for this table may ask: “How much revenue was generated in the first hour of 2014-01-01 in the city of San Francisco?”. This query is filtering a sales data set based on a Boolean expression of dimension values. In many real world data sets, dimension columns contain strings and metric columns contain numbers. Druid creates additional lookup indices for string columns such that only those rows that pertain to a particular query filter are ever scanned.

For each unique city in Table 1, we can form some representation indicating in which table rows a particular city is seen. We can store this information in a binary array where the array indices represent our rows. If a particular page is seen in a certain row, that array index is marked as 1. For example:

```
San Francisco -> rows [0, 1] -> [1] [1] [0] [0]
New York      -> rows [2, 3] -> [0] [0] [1] [1]
```

San Francisco is seen in rows 0 and 1. This mapping of column values to row indices forms an inverted index [4]. To know which rows contain San Francisco or New York, we can OR together the two arrays.

```
[0] [1] [0] [1] OR [1] [0] [1] [0] = [1] [1] [1] [1]
```

This approach of performing Boolean operations on large bitmap sets is commonly used in search engines. Druid compresses each bitmap index using the Concise algorithm [2]. All Boolean operations on top of these Concise sets are done without decompressing the set.

2.6 Query Capabilities

Druid supports many types of aggregations including double sums, long sums, minimums, maximums, and complex aggregations such as cardinality estimation and approximate quantile estimation. The results of aggregations can be combined in mathematical expressions to form other aggregations. Druid supports different query types ranging from simple aggregates for an interval time, groupBys, and approximate top-K queries.

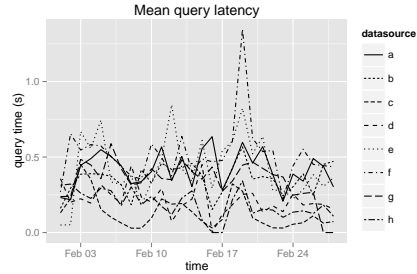


Figure 2: Query latencies of production data sources.

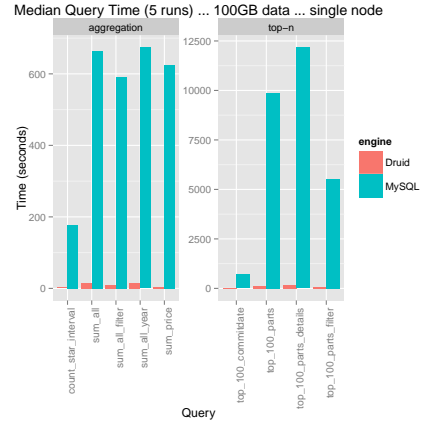


Figure 3: Druid & MySQL benchmarks – 100GB TPC-H data.

3. PERFORMANCE

Druid runs in production at several organizations, and to briefly demonstrate its performance, we have chosen to share some real world numbers for the main production cluster running at Metamarkets in early 2014. For comparison with other databases we also include results from synthetic workloads on TPC-H data.

3.1 Query Performance

Query latencies are shown in Figure 2 for a cluster hosting approximately 10.5TB of data using 1302 processing threads and 672 total cores (hyperthreaded). There are approximately 50 billion rows of data in this cluster.

The average queries per minute during this time was approximately 1000. The number of dimensions the various data sources vary from 25 to 78 dimensions, and 8 to 35 metrics. Across all the various data sources, average query latency is approximately 550 milliseconds, with 90% of queries returning in less than 1 second, 95% in under 2 seconds, and 99% of queries returning in less than 10 seconds.

Approximately 30% of the queries are standard aggregates involving different types of metrics and filters, 60% of queries are ordered group bys over one or more dimensions with aggregates, and 10% of queries are search queries and meta-data retrieval queries. The number of columns scanned in aggregate queries roughly follows an exponential distribution. Queries involving a single column are very frequent, and queries involving all columns are very rare.

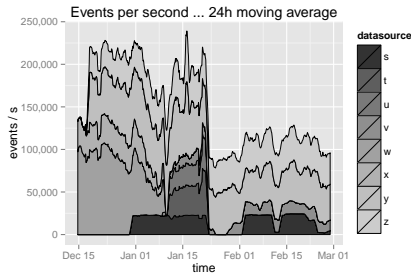


Figure 4: Combined cluster ingestion rates.

We also present Druid benchmarks on TPC-H data in Figure ?? . Most TPC-H queries do not directly apply to Druid, so we selected queries more typical of Druid’s workload to demonstrate query performance. As a comparison, we also provide the results of the same queries using MySQL using the MyISAM engine (InnoDB was slower in our experiments).

We benchmarked Druid’s scan rate at 53,539,211 rows/second/core for `select count(*)` equivalent query over a given time interval and 36,246,530 rows/second/core for a `select sum(float)` type query.

3.2 Data Ingestion Performance

To showcase Druid’s data ingestion latency, we selected several production datasources of varying dimensions, metrics, and event volumes. Druid’s data ingestion latency is heavily dependent on the complexity of the data set being ingested. The data complexity is determined by the number of dimensions in each event, the number of metrics in each event, and the types of aggregations we want to perform on those metrics.

For the given datasources, the number of dimensions vary from 5 to 35, and the number of metrics vary from 2 to 24. The peak ingestion latency we measured in production was 22914.43 events/second/core on a datasource with 30 dimensions and 19 metrics.

The latency measurements we presented are sufficient to address the our stated problems of interactivity. We would prefer the variability in the latencies to be less, which can be achieved by adding additional hardware, but we have not chosen to do so because of cost concerns.

4. DEMONSTRATION DETAILS

We would like to do an end-to-end demonstration of Druid, from setting up a cluster, ingesting data, structuring a query, and obtaining results. We would also like to showcase how to solve real-world data analysis problems with Druid and demonstrate tools that can be built on top of it, including interactive data visualizations, approximate algorithms, and machine-learning components. We already use similar tools in production.

4.1 Setup

Users will be able to set up a local Druid cluster to better understand the components and architecture of the system. Druid is designed to run on commodity hardware and Druid nodes are simply java processes that need to be started up. The local setup will allow users to ingest data from Twitter’s

public API and query it. We will also provide users access to an AWS hosted Druid cluster that contains several terabytes of Twitter data that we have been collecting for over 2 years. There are over 3 billion tweets in this data set, and new events are constantly being ingested. We will walk through a variety of different queries to demonstrate Druid’s arbitrary data-exploration capabilities.

Finally, we will teach users how to build a simple interactive dashboard on top of Druid. The dashboard will use some of Druid’s more powerful features such as approximate algorithms for quickly determining the cardinality of sets, and machine learning algorithms for scientific computing problems such as anomaly detection. These use cases represent some of the more interesting problems we use Druid for in production.

4.2 Goals

We will not only walk users through solving real-world problems with Druid and different tools that have been built on top of Druid, but also answer conference-specific questions such as what are the trending tweets and topics at VLDB, what netizens are conversing about in the general area, and even perform a sentiment analysis of VLDB. Our goal is to clearly explain why the architecture of Druid makes it highly optimal for certain types of queries, and the potential of the system as a real-time analytics platform.

5. ACKNOWLEDGMENTS

Druid could not have been built without the help of many great people in the community. We want to thank everyone that has contributed to the Druid codebase for their invaluable support.

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