

# Druid: A Real-time Analytical Data Store

Fangjin Yang, Eric Tschetter, Xavier Léauté, Nelson Ray, Gian Merlino, Deep Ganguli  
{fangjin, cheddar, xavier, nelson, gian, deep}@metamarkets.com

## ABSTRACT

Druid is an open source<sup>1</sup> data store designed for real-time exploratory analytics on large data sets. The system combines a column-oriented storage layout, a distributed, shared-nothing architecture, and an advanced indexing structure to allow for the arbitrary exploration of billion-row tables with sub-second latencies. In this paper, we describe Druid’s architecture, and detail how it supports fast aggregations, flexible filters, and low latency data ingestion.

## 1. INTRODUCTION

In recent years, the proliferation of internet technology has created a surge in machine-generated events. Individually, these events contain minimal useful information and are of low value. Given the time and resources required to extract meaning from large collections of events, many companies were willing to discard this data instead. Although infrastructure has been built to handle event based data (e.g. IBM’s Netezza[38], HP’s Vertica[6], and EMC’s Greenplum[30]), they are largely sold at high price points and are only targeted towards those companies who can afford the offering.

A few years ago, Google introduced MapReduce [12] as their mechanism of leveraging commodity hardware to index the internet and analyze logs. The Hadoop [37] project soon followed and was largely patterned after the insights that came out of the original MapReduce paper. Hadoop is currently deployed in many organizations to store and analyze large amounts of log data. Hadoop has contributed much to helping companies convert their low-value event streams into high-value aggregates for a variety of applications such as business intelligence and A-B testing.

As with a lot of great systems, Hadoop has opened our eyes to a new space of problems. Specifically, Hadoop excels at storing and providing access to large amounts of data, however, it does not make any performance guarantees around how quickly that data can be accessed. Furthermore, although Hadoop is a highly available system, performance degrades under heavy concurrent load. Lastly, while Hadoop works well for storing data, it is not optimized for ingesting data and making that data immediately readable.

Early on in the development of the Metamarkets product, we ran into each of these issues and came to the realization that Hadoop is a great back-office, batch processing, and data warehousing system. However, as a company that has product-level guarantees around query performance and data availability in a highly concurrent environment (1000+ users), Hadoop wasn’t going to meet our needs. We explored different solutions in the space, and after trying both

Relational Database Management Systems and NoSQL architectures, we came to the conclusion that there was nothing in the open source world that could be fully leveraged for our requirements.

We ended up creating Druid, an open-source, distributed, column-oriented, realtime analytical data store. In many ways, Druid shares similarities with other OLAP systems [31, 36, 23], interactive query systems [29], main-memory databases [15], and widely-known distributed data stores [8, 13, 24]. The distribution and query model also borrow ideas from current generation search infrastructure [26, 4, 5].

This paper describes the architecture of Druid, explores the various design decisions made in creating an always-on production system that powers a hosted service, and attempts to help inform anyone who faces a similar problem about a potential method of solving it. Druid is deployed in production at several technology companies<sup>2</sup>.

The structure of the paper is as follows: we first describe the problem in Section 2. Next, we detail system architecture from the point of view of how data flows through the system in Section 3. We then discuss how and why data gets converted into a binary format in Section 4. We briefly describe the query API in Section 5 and present our experimental results in Section 6. Lastly, we leave off with what we’ve learned from running Druid in production in Section 7, related work in Section 8, and conclusions in Section 9.

## 2. PROBLEM DEFINITION

Druid was originally designed to solve problems around ingesting and exploring large quantities of transactional events (log data). This form of timeseries data is commonly found in OLAP workflows and the nature of the data tends to be very append heavy. For example, consider the data shown in Table 1. Table 1 contains data for edits that have occurred on Wikipedia. Each time a user edits a page in Wikipedia, an event is generated that contains metadata about the edit. This metadata is comprised of 3 distinct components. First, there is a timestamp column indicating when the edit was made. Next, there are a set dimension columns indicating various attributes about the edit such as the page that was edited, the user who made the edit, and the location of the user. Finally, there are a set of metric columns that contain values (usually numeric) that can be aggregated, such as the number of characters added or removed in an edit.

Our goal is to rapidly compute drill-downs and aggregates over this data. We want to answer questions like “How many edits were made on the page Justin Bieber from males in San Francisco?” and “What

<sup>1</sup><https://github.com/metamx/druid>

<sup>2</sup><http://druid.io/druid.html>

**Table 1: Sample Druid data for edits that have occurred on Wikipedia.**

Timestamp	Page	Username	Gender	City	Characters Added	Characters Removed
2011-01-01T01:00:00Z	Justin Bieber	Boxer	Male	San Francisco	1800	25
2011-01-01T01:00:00Z	Justin Bieber	Reach	Male	Waterloo	2912	42
2011-01-01T02:00:00Z	Ke\$ha	Helz	Male	Calgary	1953	17
2011-01-01T02:00:00Z	Ke\$ha	Xeno	Male	Taiyuan	3194	170

is the average number of characters that were added by people from Calgary over the span of a month?”. We also want queries over any arbitrary combination of dimensions to return with sub-second latencies.

The need for Druid was facilitated by the fact that existing open source Relational Database Management Systems (RDBMS) and NoSQL key/value stores were unable to provide a low latency data ingestion and query platform for interactive applications [41]. In the early days of Metamarkets, we were focused on building a hosted dashboard that would allow users to arbitrary explore and visualize event streams. The data store powering the dashboard needed to return queries fast enough that the data visualizations built on top of it could provide users with an interactive experience.

In addition to the query latency needs, the system had to be multi-tenant and highly available. The Metamarkets product is used in a highly concurrent environment. Downtime is costly and many businesses cannot afford to wait if a system is unavailable in the face of software upgrades or network failure. Downtime for startups, who often lack proper internal operations management, can determine business success or failure.

Finally, another key problem that Metamarkets faced in its early days was to allow users and alerting systems to be able to make business decisions in “real-time”. The time from when an event is created to when that event is queryable determines how fast users and systems are able to react to potentially catastrophic occurrences in their systems. Popular open source data warehousing systems such as Hadoop were unable to provide the sub-second data ingestion latencies we required.

The problems of data exploration, ingestion, and availability span multiple industries. Since Druid was open sourced in October 2012, it been deployed as a video, network monitoring, operations monitoring, and online advertising analytics platform in multiple companies.

### 3. ARCHITECTURE

A Druid cluster consists of different types of nodes and each node type is designed to perform a specific set of things. We believe this design separates concerns and simplifies the complexity of the system. The different node types operate fairly independent of each other and there is minimal interaction between them. Hence, intra-cluster communication failures have minimal impact on data availability. To solve complex data analysis problems, the different node types come together to form a fully working system. The name Druid comes from the Druid class in many role-playing games: it is a shape-shifter, capable of taking on many different forms to fulfill various different roles in a group. The composition of and flow of data in a Druid cluster are shown in Figure 1.

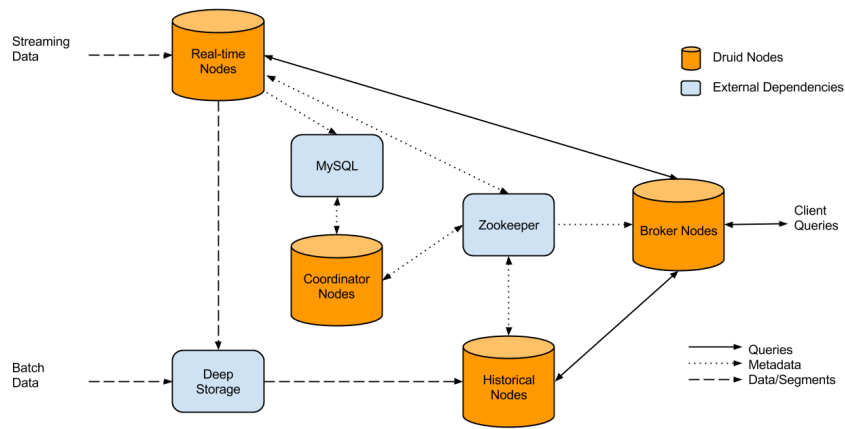
### 3.1 Real-time Nodes

Real-time nodes encapsulate the functionality to ingest and query event streams. Events indexed via these nodes are immediately available for querying. The nodes are only concerned with events for some small time range and periodically hand off immutable batches of events they’ve collected over this small time range to other nodes in the Druid cluster that are specialized in dealing with batches of immutable events. Real-time nodes leverage Zookeeper [20] for coordination with the rest of the Druid cluster. The nodes announce their online state and the data they are serving in Zookeeper.

Real-time nodes maintain an in-memory index buffer for all incoming events. These indexes are incrementally populated as new events are ingested and the indexes are also directly queryable. Druid virtually behaves as a row store for queries on events that exist in this JVM heap-based buffer. To avoid heap overflow problems, real-time nodes persist their in-memory indexes to disk either periodically or after some maximum row limit is reached. This persist process converts data stored in the in-memory buffer to a column oriented storage format described in Section 4. Each persisted index is immutable and real-time nodes load persisted indexes into off-heap memory such that they can still be queried. This process is described in detail in [34] and is illustrated in Figure 2.

On a periodic basis, each real-time node will schedule a background task that searches for all locally persisted indexes. The task merges these indexes together and builds an immutable block of data that contains all the events that have ingested by a real-time node for some span of time. We refer to this block of data as a “segment”. During the handoff stage, a real-time node uploads this segment to a permanent backup storage, typically a distributed file system such as S3 [13] or HDFS [37], which Druid refers to as “deep storage”. The ingest, persist, merge, and handoff steps are fluid; there is no data loss during any of the processes.

To better understand the flow of data through a real-time node, consider the following example. First, we start a real-time node at 13:37. The node will only accept events for the current hour or the next hour. When the node begins ingesting events, it will announce that it is serving a segment of data for a time window from 13:00 to 14:00. Every 10 minutes (the persist period is configurable), the node will flush and persist its in-memory buffer to disk. Near the end of the hour, the node will likely see events with timestamps from 14:00 to 15:00. When this occurs, the node prepares to serve data for the next hour and creates a new in-memory index. The node then announces that it is also serving a segment for data from 14:00 to 15:00. The node does not immediately merge the indexes it persisted from 13:00 to 14:00, instead it waits for a configurable window period for straggling events from 13:00 to 14:00 to come in. Having a window period minimizes the risk of data loss from delays in event delivery. At the end of the window period, the real-time node merges all persisted indexes from 13:00 to 14:00 into a single immutable segment and hands the segment off. Once this segment is loaded and queryable somewhere else in the Druid cluster,



**Figure 1: An overview of a Druid cluster and the flow of data through the cluster.**

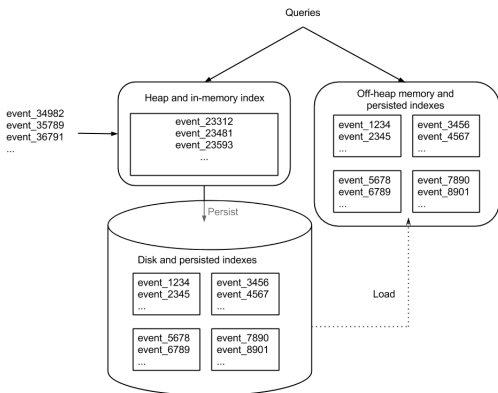
ter, the real-time node flushes all information about the data it collected for 13:00 to 14:00 and unannounces it is serving this data. This process is shown in Figure 3.

### 3.1.1 Availability and Scalability

Real-time nodes are a consumer of data and require a corresponding producer to provide the data stream. Commonly, for data durability purposes, a message bus such as Kafka [22] sits between the producer and the real-time node as shown in Figure 4. Real-time nodes ingest data by reading events from the message bus. The time from event creation to event consumption is ordinarily on the order of hundreds of milliseconds.

The purpose of the message bus in Figure 4 is two-fold. First, the message bus acts as a buffer for incoming events. A message bus such as Kafka maintains offsets indicating the position in an event stream that a consumer (a real-time node) has read up to and consumers can programmatically update these offsets. Typically, real-time nodes update this offset each time they persist their in-memory buffers to disk. In a fail and recover scenario, if a node has not lost disk, it can reload all persisted indexes from disk and continue reading events from the last offset it committed. Ingesting events from a recently committed offset greatly reduces a node's recovery time. In practice, we see real-time nodes recover from such failure scenarios in an order of seconds.

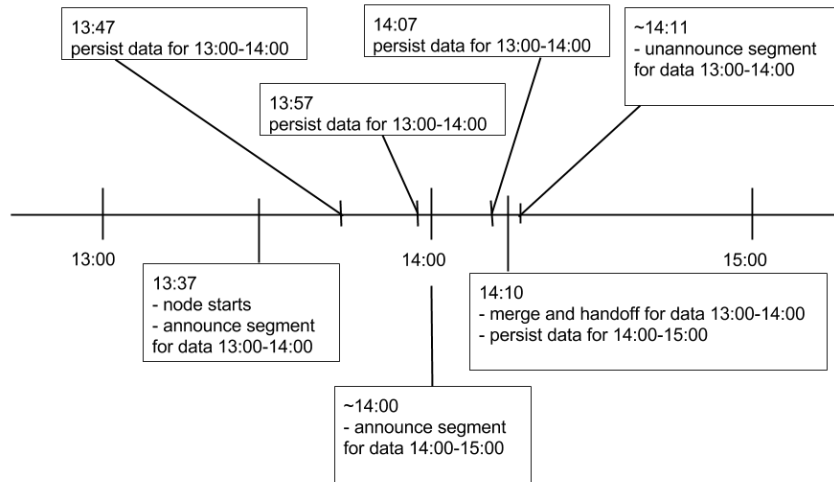
The second purpose of the message bus is to act as a single endpoint from which multiple real-time nodes can read events. Multiple real-time nodes can ingest the same set of events from the bus, thus creating a replication of events. In a scenario where a node completely fails and does not recover, replicated streams ensure that no data is lost. A single ingestion endpoint also allows for data streams for be partitioned such that multiple real-time nodes each ingest a portion of a stream. This allows additional real-time nodes to be seamlessly added. In practice, this model has allowed one of the largest production Druid clusters to be able to consume raw data at approximately 500 MB/s (150,000 events/s or 2 TB/hour).



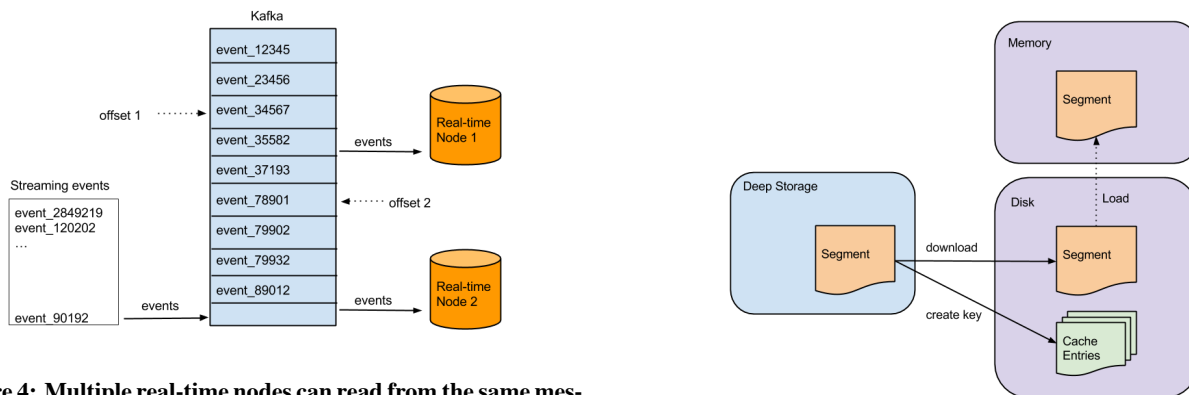
**Figure 2: Real-time nodes first buffer events in memory. On a periodic basis, the in-memory index is persisted to disk. On another periodic basis, all persisted indexes are merged together and handed off. Queries for data will hit the in-memory index and the persisted indexes.**

## 3.2 Historical Nodes

Historical nodes encapsulate the functionality to load and serve the immutable blocks of data (segments) created by real-time nodes. In many real-world workflows, most of the data loaded in a Druid cluster is immutable and hence, historical nodes are typically the main



**Figure 3: The node starts, ingests data, persists, and periodically hands data off. This process repeats indefinitely. The time intervals between different real-time node operations are configurable.**



**Figure 4: Multiple real-time nodes can read from the same message bus. Each node maintains its own offset.**

**Figure 5: Historical nodes download immutable segments from deep storage. Segments must be loaded in memory before they can be queried.**

workers of a Druid cluster. Historical nodes follow a shared-nothing architecture and there is no single point of contention among the nodes. The nodes have no knowledge of one another and are operationally simple; they only know how to load, drop, and serve immutable segments.

Similar to real-time nodes, historical nodes announce their online state and the data they are serving in Zookeeper. Instructions to load and drop segments are sent over Zookeeper and contain information about where the segment is located in deep storage and how to decompress and process the segment. Before a historical node downloads a particular segment from deep storage, it first checks a local cache that maintains information about what segments already exist on the node. If information about a segment is not present in the cache, the historical node will proceed to download the segment from deep storage. This process is shown in Figure 5. Once processing is complete, the segment is announced in Zookeeper. At this point, the segment is queryable. The local cache also allows for historical nodes to be quickly updated and restarted. On startup, the node examines its cache and immediately serves whatever data it finds.

Historical nodes can support read consistency because they only deal with immutable data. Immutable data blocks also enable a simple parallelization model: historical nodes can concurrently scan and aggregate immutable blocks without blocking.

### 3.2.1 Tiers

Historical nodes can be grouped in different tiers, where all nodes in a given tier are identically configured. Different performance and fault-tolerance parameters can be set for each tier. The purpose of tiered nodes is to enable higher or lower priority segments to be distributed according to their importance. For example, it is possible to spin up a “hot” tier of historical nodes that have a high number of cores and large memory capacity. The “hot” cluster can be configured to download more frequently accessed data. A parallel “cold” cluster can also be created with much less powerful backing hardware. The “cold” cluster would only contain less frequently accessed segments.

### 3.2.2 Availability

Historical nodes depend on Zookeeper for segment load and unload instructions. If Zookeeper becomes unavailable, historical nodes are no longer able to serve new data and drop outdated data, however, because the queries are served over HTTP, historical nodes are still be able to respond to query requests for the data they are currently serving. This means that Zookeeper outages do not impact current data availability on historical nodes.

## 3.3 Broker Nodes

Broker nodes act as query routers to historical and real-time nodes. Broker nodes understand the metadata published in Zookeeper about what segments are queryable and where those segments are located. Broker nodes route incoming queries such that the queries hit the right historical or real-time nodes. Broker nodes also merge partial results from historical and real-time nodes before returning a final consolidated result to the caller.

### 3.3.1 Caching

Broker nodes contain a cache with a LRU [32, 21] invalidation strategy. The cache can use local heap memory or an external distributed key/value store such as Memcached [17]. Each time a broker node receives a query, it first maps the query to a set of segments. Results for certain segments may already exist in the cache and there is no need to recompute them. For any results that do not exist in the cache, the broker node will forward the query to the correct historical and real-time nodes. Once historical nodes return their results, the broker will cache these results on a per segment basis for future use. This process is illustrated in Figure 6. Real-time data is never cached and hence requests for real-time data will always be forwarded to real-time nodes. Real-time data is perpetually changing and caching the results would be unreliable.

The cache also acts as an additional level of data durability. In the event that all historical nodes fail, it is still possible to query results if those results already exist in the cache.

### 3.3.2 Availability

In the event of a total Zookeeper outage, data is still queryable. If broker nodes are unable to communicate to Zookeeper, they use their last known view of the cluster and continue to forward queries to real-time and historical nodes. Broker nodes make the assumption that the structure of the cluster is the same as it was before the outage. In practice, this availability model has allowed our Druid cluster to continue serving queries for a significant period of time while we diagnosed Zookeeper outages.

## 3.4 Coordinator Nodes

Druid coordinator nodes are primarily in charge of data management and distribution on historical nodes. The coordinator nodes tell historical nodes to load new data, drop outdated data, replicate data, and move data to load balance. Druid uses a multi-version concurrency control swapping protocol for managing immutable segments in order to maintain stable views. If any immutable segment contains data that is wholly obsoleted by newer segments, the outdated segment is dropped from the cluster. Coordinator nodes undergo a leader-election process that determines a single node that runs the coordinator functionality. The remaining coordinator nodes act as redundant backups.

A coordinator node runs periodically to determine the current state of the cluster. It makes decisions by comparing the expected state of

the cluster with the actual state of the cluster at the time of the run. As with all Druid nodes, coordinator nodes maintain a Zookeeper connection for current cluster information. Coordinator nodes also maintain a connection to a MySQL database that contains additional operational parameters and configurations. One of the key pieces of information located in the MySQL database is a table that contains a list of all segments that should be served by historical nodes. This table can be updated by any service that creates segments, for example, real-time nodes. The MySQL database also contains a rule table that governs how segments are created, destroyed, and replicated in the cluster.

### 3.4.1 Rules

Rules govern how historical segments are loaded and dropped from the cluster. Rules indicate how segments should be assigned to different historical node tiers and how many replicates of a segment should exist in each tier. Rules may also indicate when segments should be dropped entirely from the cluster. Rules are usually set for a period of time. For example, a user may use rules to load the most recent one month's worth of segments into a "hot" cluster, the most recent one year's worth of segments into a "cold" cluster, and drop any segments that are older.

The coordinator nodes load a set of rules from a rule table in the MySQL database. Rules may be specific to a certain data source and/or a default set of rules may be configured. The coordinator node will cycle through all available segments and match each segment with the first rule that applies to it.

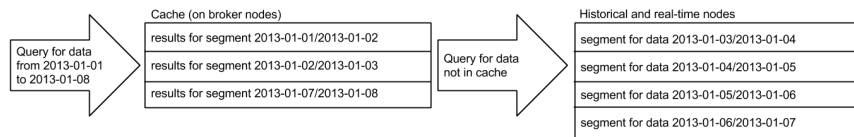
### 3.4.2 Load Balancing

In a typical production environment, queries often hit dozens or even hundreds of segments. Since each historical node has limited resources, segments must be distributed among the cluster to ensure that the cluster load is not too imbalanced. Determining optimal load distribution requires some knowledge about query patterns and speeds. Typically, queries cover recent segments spanning contiguous time intervals for a single data source. On average, queries that access smaller segments are faster.

These query patterns suggest replicating recent historical segments at a higher rate, spreading out large segments that are close in time to different historical nodes, and co-locating segments from different data sources. To optimally distribute and balance segments among the cluster, we developed a cost-based optimization procedure that takes into account the segment data source, recency, and size. The exact details of the algorithm are beyond the scope of this paper and may be discussed in future literature.

### 3.4.3 Replication

Coordinator nodes may tell different historical nodes to load copies of the same segment. The number of replicates in each tier of the historical compute cluster is fully configurable. Setups that require high levels of fault tolerance can be configured to have a high number of replicas. Replicated segments are treated the same as the originals and follow the same load distribution algorithm. By replicating segments, single historical node failures are transparent in the Druid cluster. We use this property for software upgrades. We can seamlessly take a historical node offline, update it, bring it back up, and repeat the process for every historical node in a cluster. Over the last two years, we have never taken downtime in our Druid cluster for software upgrades.



**Figure 6: Broker nodes cache per segment results. Every Druid query is mapped to a set of segments. Queries often combine cached segment results with those that need to be computed on historical and real-time nodes.**

### 3.4.4 Availability

Druid coordinator nodes have two external dependencies: Zookeeper and MySQL. Coordinator nodes rely on Zookeeper to determine what historical nodes already exist in the cluster. If Zookeeper becomes unavailable, the coordinator will no longer be able to send instructions to assign, balance, and drop segments. However, these operations do not affect data availability at all.

The design principle for responding to MySQL and Zookeeper failures is the same: if an external dependency responsible for coordination fails, the cluster maintains the status quo. Druid uses MySQL to store operational management information and segment metadata information about what segments should exist in the cluster. If MySQL goes down, this information becomes unavailable to coordinator nodes. However, this does not mean data itself is unavailable. If coordinator nodes cannot communicate to MySQL, they will cease to assign new segments and drop outdated ones. Broker, historical, and real-time nodes are still queryable during MySQL outages.

## 4. STORAGE FORMAT

Data tables in Druid (called *data sources*) are collections of timestamped events and partitioned into a set of segments, where each segment is typically 5–10 million rows. Formally, we define a segment as a collection of rows of data that span some period in time. Segments represent the fundamental storage unit in Druid and replication and distribution are done at a segment level.

Druid always requires a timestamp column as a method of simplifying data distribution policies, data retention policies, and first-level query pruning. Druid partitions its data sources into well-defined time intervals, typically an hour or a day, and may further partition on values from other columns to achieve the desired segment size. For example, partitioning the data in Table 1 by hour results in two segments for 2011-01-01, and partitioning the data by day results in a single segment. The time granularity to partition segments is a function of data volume and time range. A data set with timestamps spread over a year is better partitioned by day, and a data set with timestamps spread over a day is better partitioned by hour.

Segments are uniquely identified by a data source identifier, the time interval of the data, and a version string that increases whenever a new segment is created. The version string indicates the freshness of segment data; segments with later versions have newer views of data (over some time range) than segments with older versions. This segment metadata is used by the system for concurrency control; read operations always access data in a particular time range from the segments with the latest version identifiers for that time range.

Druid segments are stored in a column orientation. Given that Druid is best used for aggregating event streams (all data going into Druid must have a timestamp), the advantages storing aggregate informa-

tion as columns rather than rows are well documented [1]. Column storage allows for more efficient CPU usage as only what is needed is actually loaded and scanned. In a row oriented data store, all columns associated with a row must be scanned as part of an aggregation. The additional scan time can introduce significant performance degradations [1].

Druid has multiple column types to represent various data formats. Depending on the column type, different compression methods are used to reduce the cost of storing a column in memory and on disk. In the example given in Table 1, the page, user, gender, and city columns only contain strings. Storing strings directly is unnecessarily costly and string columns can be dictionary encoded instead. Dictionary encoding is a common method to compress data and has been used in other data stores such as PowerDrill [18]. In the example in Table 1, we can map each page to a unique integer identifier.

```
Justin Bieber -> 0
Ke$ha -> 1
```

This mapping allows us to represent the page column as an integer array where the array indices correspond to the rows of the original data set. For the page column, we can represent the unique pages as follows:

```
[0, 0, 1, 1]
```

The resulting integer array lends itself very well to compression methods. Generic compression algorithms on top of encodings are extremely common in column-stores. Druid uses the LZ4 [25] compression algorithm.

Similar compression methods can be applied to numeric columns. For example, the characters added and characters removed columns in Table 1 can also be expressed as individual arrays.

```
Characters Added -> [1800, 2912, 1953, 3194]
Characters Removed -> [25, 42, 17, 170]
```

In this case, we compress the raw values as opposed to their dictionary representations.

### 4.1 Indices for Filtering Data

In many real world OLAP workflows, queries are issued for the aggregated results of some set of metrics where some set of dimension specifications are met. An example query is: "How many Wikipedia edits were done by users in San Francisco who are also male?". This query is filtering the Wikipedia data set in Table 1 based on a Boolean expression of dimension values. In many real

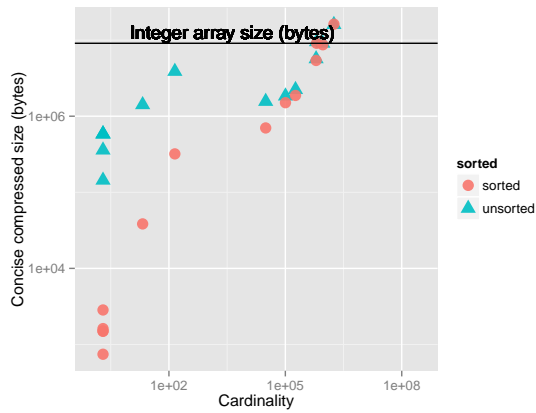


Figure 7: Integer array size versus Concise set size.

world data sets, dimension columns contain strings and metric columns contain numeric values. Druid creates additional lookup indices for string columns such that only those rows that pertain to a particular query filter are ever scanned.

Let us consider the page column in Table 1. For each unique page in Table 1, we can form some representation indicating in which table rows a particular page is seen. We can store this information in a binary array where the array indices represent our rows. If a particular page is seen in a certain row, that array index is marked as 1. For example:

```
Justin Bieber -> rows [0, 1] -> [1][1][0][0]
Ke$ha -> rows [2, 3] -> [0][0][1][1]
```

Justin Bieber is seen in rows 0 and 1. This mapping of column values to row indices forms an inverted index [40]. To know which rows contain Justin Bieber or Ke\$ha, we can OR together the two arrays.

```
[0][1][0][1] OR [1][0][1][0] = [1][1][1][1]
```

This approach of performing Boolean operations on large bitmap sets is commonly used in search engines. Bitmap indices for OLAP workloads is described in detail in [33]. Bitmap compression algorithms are a well-defined area of research and often utilize run-length encoding. Popular algorithms include Byte-aligned Bitmap Code [3], Word-Aligned Hybrid (WAH) code [45], and Partitioned Word-Aligned Hybrid (PWAH) compression [43]. Druid opted to use the Concise algorithm [11] as it can outperform WAH by reducing the size of the compressed bitmaps by up to 50%. Figure 7 illustrates the number of bytes using Concise compression versus using an integer array. The results were generated on a cc2.8xlarge system with a single thread, 2G heap, 512m young gen, and a forced GC between each run. The data set is a single day's worth of data collected from the Twitter garden hose [42] data stream. The data set contains 2,272,295 rows and 12 dimensions of varying cardinality. As an additional comparison, we also resorted the data set rows to maximize compression.

In the unsorted case, the total Concise size was 53,451,144 bytes and the total integer array size was 127,248,520 bytes. Overall,

Concise compressed sets are about 42% smaller than integer arrays. In the sorted case, the total Concise compressed size was 43,832,884 bytes and the total integer array size was 127,248,520 bytes. What is interesting to note is that after sorting, global compression only increased minimally. The total Concise set size to total integer array size is 34%. It is also interesting to note that as the cardinality of a dimension approaches the total number of rows in a data set, integer arrays require less space than Concise sets and become a better alternative.

## 4.2 Storage Engine

Druid's persistence components allows for different storage engines to be plugged in, similar to Dynamo [13]. These storage engines may store data in an entirely in-memory structure such as the JVM heap or in memory-mapped structures. The ability to swap storage engines allows for Druid to be configured depending on a particular application's specifications. An in-memory storage engine may be operationally more expensive than a memory-mapped storage engine but could be a better alternative if performance is critical. By default, a memory-mapped storage engine is used.

When using a memory-mapped storage engine, Druid relies on the operating system to page segments in and out of memory. Given that segments can only be scanned if they are loaded in memory, a memory-mapped storage engine allows recent segments to retain in memory whereas segments that are never queried are paged out. The main drawback with using the memory-mapped storage engine is when a query requires more segments to be paged into memory than a given node has capacity for. In this case, query performance will suffer from the cost of paging segments in and out of memory.

## 5. QUERY API

Druid has its own query language and accepts queries as POST requests. Broker, historical, and real-time nodes all share the same query API.

The body of the POST request is a JSON object containing key-value pairs specifying various query parameters. A typical query will contain the data source name, the granularity of the result data, time range of interest, the type of request, and the metrics to aggregate over. The result will also be a JSON object containing the aggregated metrics over the time period.

Most query types will also support a filter set. A filter set is a Boolean expression of dimension name and value pairs. Any number and combination of dimensions and values may be specified. When a filter set is provided, only the subset of the data that pertains to the filter set will be scanned. The ability to handle complex nested filter sets is what enables Druid to drill into data at any depth.

The exact query syntax depends on the query type and the information requested. A sample count query over a week of data is as follows:

```

{
  "queryType" : "timeseries",
  "dataSource" : "wikipedia",
  "intervals" : "2013-01-01/2013-01-08",
  "filter" : {
    "type" : "selector",
    "dimension" : "page",
    "value" : "Ke$ha"
  },
  "granularity" : "day",
  "aggregations" : [ {
    "type" : "count",
    "name" : "rows"
  } ]
}

```

The query shown above will return a count of the number of rows in the Wikipedia datasource from 2013-01-01 to 2013-01-08, filtered for only those rows where the value of the "page" dimension is equal to "Ke\$ha". The results will be bucketed by day and will be a JSON array of the following form:

```

[ {
  "timestamp": "2012-01-01T00:00:00.000Z",
  "result": {
    "rows": 393298
  }
},
{
  "timestamp": "2012-01-02T00:00:00.000Z",
  "result": {
    "rows": 382932
  }
},
...
{
  "timestamp": "2012-01-07T00:00:00.000Z",
  "result": {
    "rows": 1337
  }
} ]

```

Druid supports many types of aggregations including double sums, long sums, minimums, maximums, and several others. Druid also supports complex aggregations such as cardinality estimation and approximate quantile estimation. The results of aggregations can be combined in mathematical expressions to form other aggregations. The query API is highly customizable and can be extended to filter and group results based on almost any arbitrary condition. It is beyond the scope of this paper to fully describe the query API but more information can be found online<sup>3</sup>.

At the time of writing, the query language does not support joins. Although the storage format is able to support joins, we've targeted Druid at user-facing workloads that must return in a matter of seconds, and as such, we've chosen to not spend the time to implement joins as it has been our experience that requiring joins on your queries often limits the performance you can achieve.

<sup>3</sup><http://druid.io/docs/latest/Querying.html>

**Table 2: Dimensions and metrics of the 8 most queried Druid data sources in production.**

Data Source	Dimensions	Metrics
a	25	21
b	30	26
c	71	35
d	60	19
e	29	8
f	30	16
g	26	18
h	78	14

## 6. PERFORMANCE

Druid runs in production at several organizations, and to demonstrate its performance, we've chosen to share some real world numbers of the production cluster at Metamarkets. The date range of the data is for February 2014.

### 6.1 Query Performance

Druid query performance can vary significantly depending on the actual query being issued. For example, determining the approximate cardinality of a given dimension is a much more expensive operation than a simple sum of a metric column. Similarly, sorting the values of a high cardinality dimension based on a given metric is much more expensive than a simple count over a time range. Furthermore, the time range of a query and the number of metric aggregators in the query will contribute to query latency. Instead of going into full detail about every query issued in our production cluster, we've instead chosen to showcase a higher level view of average latencies in our cluster. We selected 8 of our most queried data sources, described in Table 2.

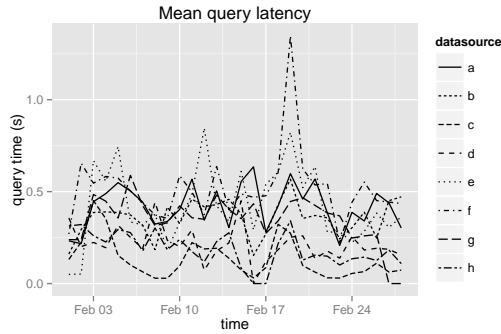
Some more details of our results:

- The results are from a "hot" tier in our production cluster. We run several tiers of varying performance in production.
- There is approximately 10.5TB of RAM available in the "hot" tier and approximately 10TB of segments loaded (including replication). Collectively, there are about 50 billion Druid rows in this tier. Results for every data source are not shown.
- The hot tier uses Xeon E5-2670 processors and consists of 1302 processing threads and 672 total cores (hyperthreaded).
- A memory-mapped storage engine was used (the machine was configured to memory map the data instead of loading it into the Java heap.)

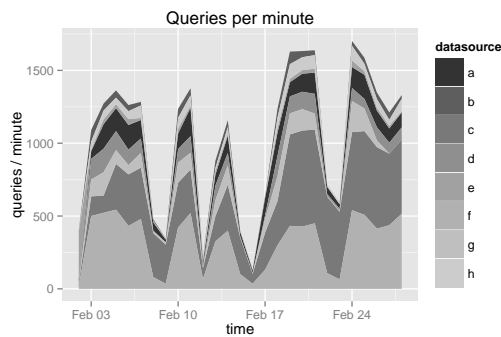
The average query latency is shown in Figure 8 and the queries per minute is shown in Figure 9. We can see that across the various data sources, the average query latency is approximately 540ms. The 90th percentile query latency across these data sources is < 1s, the 95th percentile is < 2s, and the 99th percentile is < 10s. The percentiles are shown in Figure 10. It is very possible to decrease query latencies by adding additional hardware, but we have not chosen to do so because infrastructure cost is still a consideration.

We also present Druid benchmarks with TPC-H data. Our setup used Amazon EC2 m3.2xlarge (CPU: Intel(R) Xeon(R) CPU E5-2680

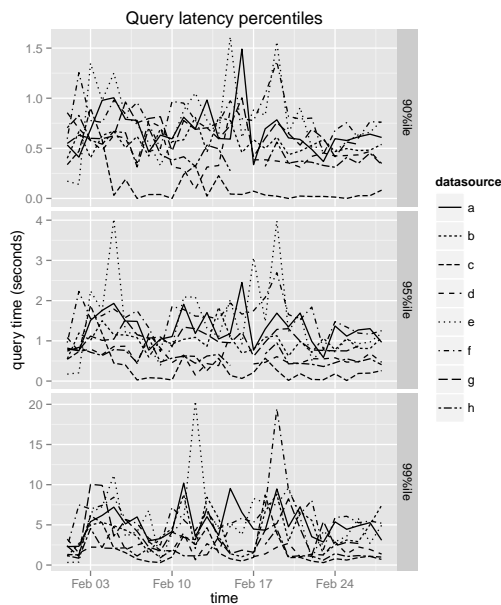




**Figure 8: Druid production cluster average query latencies for multiple data sources.**



**Figure 9: Druid production cluster queries per minute for multiple data sources.**



**Figure 10: Druid production cluster 90th, 95th, and 99th query latency percentiles for the 8 most queried data sources.**



**Figure 11: Druid and MySQL (MyISAM) benchmarks with the TPC-H 1 GB data set.**

v2 @ 2.80GHz) instances for historical nodes. Most TPC-H queries do not directly apply to Druid, so we selected similar queries to demonstrate Druid’s query performance. As a comparison, we also provide the results of the same queries using MySQL with MyISAM (InnoDB was slower in our experiments). Our MySQL setup was an Amazon RDS instance that also ran on an m3.2xlarge node. We selected MySQL to benchmark against because of its universal popularity. We choose not to select another open source column store because we were not confident we could correctly tune it for optimal performance. The results for the 1 GB TPC-H data set are shown in Figure 11 and the results of the 100 GB data set are shown in Figure 12. We benchmarked Druid’s scan rate at 53,539,211.1 rows/second/core for count(\*) over a given interval and 36,246,530 rows/second/core for an aggregation involving floats.

Finally, we present our results of scaling Druid to meet increasing data volumes with the TPC-H 100 GB data set. Our distributed cluster used Amazon EC2 c3.2xlarge (Intel(R) Xeon(R) CPU E5-2670 v2 @ 2.50GHz) instances for broker nodes. We observe that when we increased the number of cores from 8 to 48, we do not always display linear scaling. The increase in speed of a parallel computing system is often limited by the time needed for the sequential operations of the system, in accordance with Amdahl’s law [2]. Our query results and query speedup are shown in Figure 13.

## 6.2 Data Ingestion Performance

To showcase Druid’s data ingestion latency, we selected several production datasources of varying dimensions, metrics, and event volumes. Our production ingestion setup is as follows:

- Total RAM: 360 GB
- Total CPU: 12 x Intel Xeon E5-2670 (96 cores)
- Note: In this setup, several other data sources were being ingested and many other Druid related ingestion tasks were running across these machines.

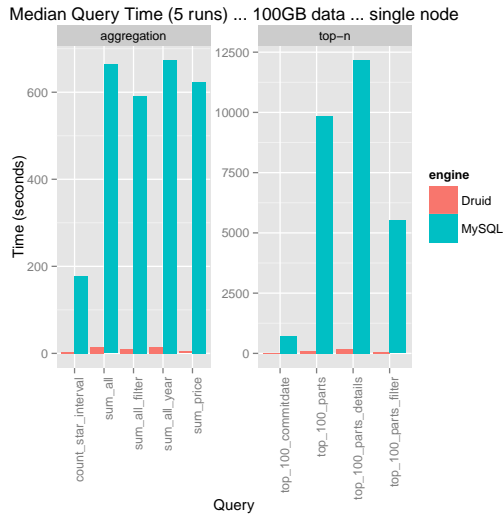


Figure 12: Druid and MySQL (MyISAM) benchmarks with the TPC-H 100 GB data set.

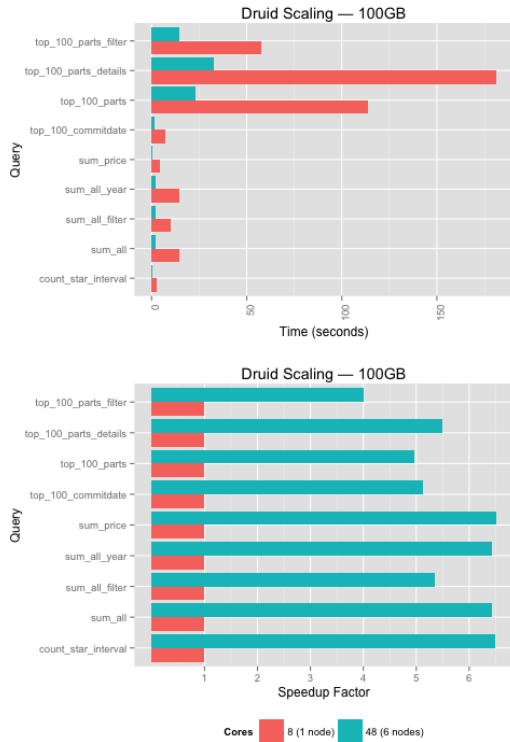


Figure 13: Scaling a Druid cluster with the TPC-H 100 GB data set.

Table 3: Dimensions, metrics, and peak throughputs of various ingested data sources.

Data Source	Dims	Mets	Peak Throughput (events/sec)
s	7	2	28334.60
t	10	7	68808.70
u	5	1	49933.93
v	30	10	22240.45
w	35	14	135763.17
x	28	6	46525.85
y	33	24	162462.41
z	33	24	95747.74

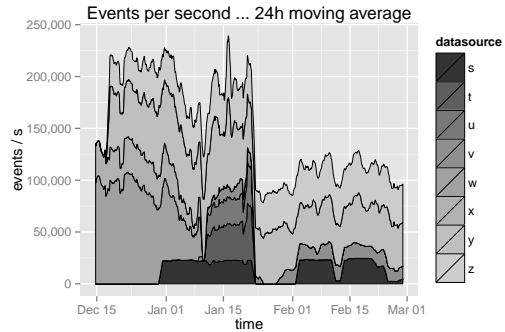


Figure 14: Druid production cluster ingestion rates for multiple data sources.

Druid’s data ingestion latency is heavily dependent on the complexity of the data set being ingested. The data complexity is determined by the number of dimensions in each event, the number of metrics in each event, and the types of aggregations we want to perform on those metrics. With the most basic data set (one that only has a timestamp column), our setup can ingest data at a rate of 800,000 events/sec/core, which is really just a measurement of how fast we can deserialize events. Real world data sets are never this simple. A description of the data sources we selected is shown in Table 3.

We can see that based on the descriptions in Table 3, latencies vary significantly and the ingestion latency is not always a factor of the number of dimensions and metrics. We see some lower latencies on simple data sets because that was the rate that the data producer was delivering data. The results are shown in Figure 14. We define throughput as the number of events a real-time node can ingest and also make queryable. If too many events are sent to the real-time node, those events are blocked until the real-time node has capacity to accept them.

The peak ingestion latency we measured in production was 22914.43 events/sec/core on an Amazon EC2 cc2.8xlarge. The data source had 30 dimensions and 19 metrics.

## 7. DRUID IN PRODUCTION

Over the last few years, we’ve gained tremendous knowledge about handling production workloads, setting up correct operational monitoring, integrating Druid with other products as part of a more sophisticated data analytics stack, and distributing data to handle entire data center outages. One of the most important lessons we’ve learned is that no amount of testing can accurately simulate a production environment, and failures will occur for every imaginable

and unimaginable reason. Interestingly, most of our most severe crashes were due to misunderstanding the impacts a seemingly small feature would have on the overall system.

Some of our more interesting observations include:

- Druid is often used in production to power exploratory dashboards. Many users of exploratory dashboards are not from technical backgrounds, and they often issue queries without understanding the impacts to the underlying system. For example, some users become impatient that their queries for terabytes of data do not return in milliseconds and continuously refresh their dashboard view, generating heavy load to Druid. This type of usage forced Druid to defend itself against expensive repetitive queries.
- Cluster query performance benefits from multitenancy. Hosting every production datasource in the same cluster leads to better data parallelization as additional nodes are added.
- Even if you provide users with the ability to arbitrarily explore data, they often only have a few questions in mind. Caching is extremely important in this case, and we see a very high cache hit rates.
- When using a memory mapped storage engine, even a small amount of paging data from disk can severely impact query performance. SSDs greatly mitigate this problem.
- Leveraging approximate algorithms can greatly reduce data storage costs and improve query performance. Many users do not care about exact answers to their questions and are comfortable with a few percentage points of error.

## 7.1 Operational Monitoring

Proper monitoring is critical to run a large scale distributed cluster. Each Druid node is designed to periodically emit a set of operational metrics. These metrics may include system level data such as CPU usage, available memory, and disk capacity, JVM statistics such as garbage collection time, and heap usage, or node specific metrics such as segment scan time, cache hit rates, and data ingestion latencies. For each query, Druid nodes can also emit metrics about the details of the query such as the number of filters applied, or the interval of data requested.

Metrics can be emitted from a production Druid cluster into a dedicated metrics Druid cluster. Queries can be made to the metrics Druid cluster to explore production cluster performance and stability. Leveraging a dedicated metrics cluster has allowed us to find numerous production problems, such as gradual query speed degradations, less than optimally tuned hardware, and various other system bottlenecks. We also use a metrics cluster to analyze what queries are made in production. This analysis allows us to determine what our users are most often doing and we use this information to drive our road map.

## 7.2 Pairing Druid with a Stream Processor

At the time of writing, Druid can only understand fully denormalized data streams. In order to provide full business logic in production, Druid can be paired with a stream processor such as Apache Storm [28]. A Storm topology consumes events from a data stream, retains only those that are “on-time”, and applies any relevant business logic. This could range from simple transformations, such as

id to name lookups, up to complex operations such as multi-stream joins. The Storm topology forwards the processed event stream to Druid in real-time. Storm handles the streaming data processing work, and Druid is used for responding to queries for both real-time and historical data.

## 7.3 Multiple Data Center Distribution

Large scale production outages may not only affect single nodes, but entire data centers as well. The tier configuration in Druid coordinator nodes allow for segments to be replicated across multiple tiers. Hence, segments can be exactly replicated across historical nodes in multiple data centers. Similarly, query preference can be assigned to different tiers. It is possible to have nodes in one data center act as a primary cluster (and receive all queries) and have a redundant cluster in another data center. Such a setup may be desired if one data center is situated much closer to users.

## 8. RELATED WORK

Cattell [7] maintains a great summary about existing Scalable SQL and NoSQL data stores. Hu [19] contributed another great summary for streaming databases. Druid feature-wise sits somewhere between Google’s Dremel [29] and PowerDrill [18]. Druid has most of the features implemented in Dremel (Dremel handles arbitrary nested data structures while Druid only allows for a single level of array-based nesting) and many of the interesting compression algorithms mentioned in PowerDrill.

Although Druid builds on many of the same principles as other distributed columnar data stores [16], many of these data stores are designed to be more generic key-value stores [24] and do not support computation directly in the storage layer. There are also other data stores designed for some of the same of the data warehousing issues that Druid is meant to solve. These systems include in-memory databases such as SAP’s HANA [15] and VoltDB [44]. These data stores lack Druid’s low latency ingestion characteristics. Druid also has native analytical features baked in, similar to [35], however, Druid allows system wide rolling software updates with no downtime.

Druid is similar to [39, 9] in that it has two subsystems, a read-optimized subsystem in the historical nodes and a write-optimized subsystem in real-time nodes. Real-time nodes are designed to ingest a high volume of append heavy data, and do not support data updates. Unlike the two aforementioned systems, Druid is meant for OLAP transactions and not OLTP transactions.

Druid’s low latency data ingestion features share some similarities with Trident/Storm [28] and Streaming Spark [46], however, both systems are focused on stream processing whereas Druid is focused on ingestion and aggregation. Stream processors are great complements to Druid as a means of pre-processing the data before the data enters Druid.

There are a class of systems that specialize in queries on top of cluster computing frameworks. Shark [14] is such a system for queries on top of Spark, and Cloudera’s Impala [10] is another system focused on optimizing query performance on top of HDFS. Druid historical nodes download data locally and only work with native Druid indexes. We believe this setup allows for faster query latencies.

Druid leverages a unique combination of algorithms in its architecture. Although we believe no other data store has the same set

of functionality as Druid, some of Druid’s optimization techniques such as using inverted indices to perform fast filters are also used in other data stores [27].

## 9. CONCLUSIONS

In this paper, we presented Druid, a distributed, column-oriented, real-time analytical data store. Druid is designed to power high performance applications and is optimized for low query latencies. Druid supports streaming data ingestion and is fault-tolerant. We discussed how Druid benchmarks and summarized key architecture aspects such as the storage format, query language, and general execution.

## 10. ACKNOWLEDGEMENTS

Druid could not have been built without the help of many great engineers at Metamarkets and in the community. We want to thank everyone that has contributed to the Druid codebase for their invaluable support.

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